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CHAPTER 3. VECTOR ANALYSIS 3.1.3 Position and Distance Vectors  $z_2, y_2, z_1, y_1, x_1, x_2, x, y, R_1, R_2, R_{12}, z, P_1 = (x_1, y_1, z_1), P_2 = (x_2, y_2, z_2), O$  Figure 3-4 Distance vector  $R_{12} = P_1P_2 = R_2 - R_1$ , where  $R_1$  and  $R_2$  are the position vectors of points  $P_1$  and  $P_2$ , respectively. Figure 3.3: The notion of the position vector to a point,  $P$

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Elementary Vector Analysis, Prof. Dr. Nawazish Ali Shah  
 $\hat{v} = \text{unit vector along } dr$  Chapter IV: Vector Analysis In this chapter we shall be working primarily in the Cartesian system. Unless stated otherwise assume the system is Cartesian and any transformation, A, to another system is a rotation. Recall: in Cartesian systems,  $g = 1$ ;  $F_i = g_{ij} F_j = \delta_{ij} F_j$ .

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